

Size(L \times W \times H): 46 mm \times 71 mm \times 10 mm

Weight: 15g

Features

Full-constellation multi-frequency

Support GPS,BDS-2,BDS-3,GLONASS,Galileo,

NavIC, QZSS and SBAS

Unique Dual-engine RTK technology

Support INS+GNSS navigation

Support L-Band* and S Band

Support CAN protocol*

50Hz data output*

Dual-engine RTK Technology

Embedded with advanced Dual-Engine RTK technology, observations from primary antenna and secondary antenna are transferred to two processors where RTK are computed independenty. The robustness of system is improved as redundant measurements from a secondary antenna can significantly improve the avaiability of the positioning result in complex environments.

Flexible Integration

K827N is easy for integration with its 1.8W lower power consumption and smallsize.With support of CAN protocol,K827N can meet demands in automobile electric field.



K827N GNSS Board

Advanced Anti-interference Technology

Based on our latest QUANTUM III SoC chip with outstanding self-adaptive Anti-interference Technology,K827N can suppress the wideband,narrowband and continuous-wave interference.It can provide users with high-quality observing data in the complex electromagnetic environment.

On Board IMU

K827N combines GNSS and IMU to deliver precise positioning in challenging environment, such as urban canyons, under trees or bridges. When losing GNSS signal, it can keep centimeter level positioning in 3s and meter-level in 10s.

Strong Compatibility

Designed with standard I/O and pin definition, the K827N is compatible with mainstream GNSS boards from physical to data format, ensuring a seamlessly replacement for customers who use boards on worldwide standard 20pins to 28pins.

Dual-antenna Input

With dual antenna design, K827N can deliver robust positioning and heading. It is capable of providing centimeter-accuracy positioning and high-precision heading both in static and dynamic scenes.

Full-constellation and Multi-frequency

K827N can track all the current and planned GNSS constellations, including GPS,BDS-2,BDS-3,GLONASS,Galileo, NavIC,QZSS and SBAS.Your GNSS solutions will never be outdated with K827N GNSS boards.

Positioning	
GPS	L1C/A,L1C,L2P,L2C,L5
BDS-2	B1,B2I,B3I
BDS-3	B1I,B3I,B1C,B2a,B2b
GLONASS	G1,G2,G3*
Galileo	E1,E5b,E5a,E5AltBoC*,E6c
QZSS	L1C/A,L2C,L5,L1C*
SBAS	L1C/A
NavIC	L5, S Band
L-band*	

Heading (& Positioning 2)		
GPS	L1C/A,L1C,L2P,L2C,L5	
BDS-2	B1,B2I,B3I	
BDS-3	B1I,B3I,B1C,B2a,B2b	
GLONASS	G1,G2,G3*	
Galileo	E1,E5b,E5a,E5AltBoC*,E6c	
QZSS	L1C/A,L2C,L5,L1C*	

Performance Specifications	
Cold Start	<20s (Adding Acceleration Capture Module)
Hot Start (with RTC)	<10s (Typical)
Reacquisition	<1s
RTK Initialization time	<5s (baseline<10km)
Initialization Reliability	>99.9%
Velocity Accuracy	≤0.02m/s (PDOP≤4)
Acceleration	4 g
Overload	15 g
Time accuracy	20 ns

Heading Specification	fication	
Azimuth	0.15°/R	
Roll or Pitch	0.25°/R	

Positioning Specification	ecification	
Single Baseline RTK	8 mm+1 ppm Horizontal 15mm+1 ppm Vertical	
Post Processing	2.5 mm+1 ppm Horizontal 5mm+1 ppm Vertical	
DGPS	<0.4m RMS	
SBAS	1m 3D RMS	
Standalone	1.5m 3D RMS	

[&]quot;*"upgradeable

Data Format	
Correction data I/O	RTCM2X,3X,CMR (GPS only),CMR+(GPS only)
Position data output	-ASCII: NMEA-0183 GGA, GSA, GSV, RMC, HDT, VHD, ZDA, VTG, GST, GLL; PTNL, PJK; PTNL, AVR; PTNL, GGK -ComNav Binary -Position data output rate: 1 Hz, 2 Hz, 5 Hz, 10Hz,20Hz

Antenna Interface	
Impedance Matching	50 Ω
LNA Power External	+3.3V~+5.0V±5%VDC@0-100mA
LNA Gain	20~35dB
Physical	
Size	46mm×71mm×10mm
Weight	15.0g
Hardware interface	28pin
Environmental	
Working temperature	-40 °C to + 85 °C
Storage temperature	-55 °C to + 95 °C

Electrical	Electrical		
Input voltage	+3.3V~5.0V±5%DC @0~100mA		
Power consumption	1.8 W (Anti-interference off) Set anti-interference on consumes more about 0.2w		
Software			
ComNav Compass Receiv	ver Utility software		
0 0 1 11 11	0		

Optional Accessories		
Compass Solution software		
0 0 . 1 . (' ('		

AT-series GNSS antenna
Evaluation Kit
5m/10m RF Cables

Communications		
LVTTL ports	х3	
SPI	x2	
Event Marker input	x2	
Pulse Per Second(PPS)output	x1	
Indicator pins show the working status	х3	













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^{1.}R(meter)is the length of two GNSS antennas.