

GNSS solutions at any level

New product launch event

September 27 | 20:00 UTC+8

online event









Make your work easier and more efficient

ComNav Technology develops and manufactures GNSS OEM boards, Receivers and Solutions for high-precision positioning applications worldwide.





10 years of innovation



K726



K803





K501

K708



K823



K802



Diversified applications













Precision agriculture Surveying & Mapping

IoT

UAV

CORS

Machine Control



K827 GNSS Board

One single board with two RTK engine



Highly compatible

The same size as mainstream boards



Size: 46mm×71mm×10mm Power consumption: 1.8W



2 x 14pin

3 LVTTL ports

2 SPI

2 Event Marker input

1 PPS

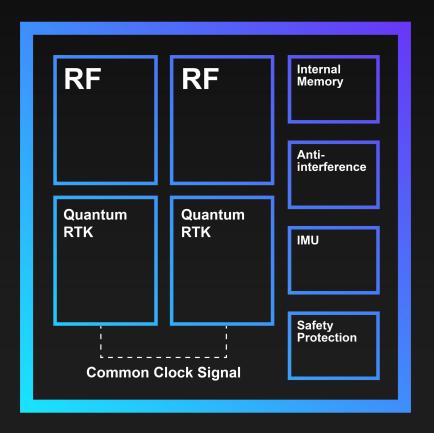
3 indicator pins



Maximum positioning availability

Dual-engine RTK technology

- One board with two independent RTK engines
- Enhanced robustness of system
- Improved availability of the positioning result in complex environment





Strong signal tracking capability

Full-constellation Multi-frequency

Positioning	Heading (Positioning 2)
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GPS: L1C/A, L1C, L2P, L2C, L5

BDS-2: B11, B21, B31

BDS-3: B11, B31, B1C, B2a, B2b

GLONASS: G1, G2, G3*

Galileo: E1, E5b, E5a, E5 AltBoC*, E6c

QZSS: L1C/A, L2C, L5, L1C*

SBAS: L1C/A

IRNSS: L5

L-band*

GPS: L1C/A, L1C, L2P, L2C, L5

BDS-2: B11, B21, B31

BDS-3: B11, B31, B1C, B2a, B2b

GLONASS: G1, G2, G3*

Galileo: E1, E5b, E5a, E5 AltBoC*, E6c

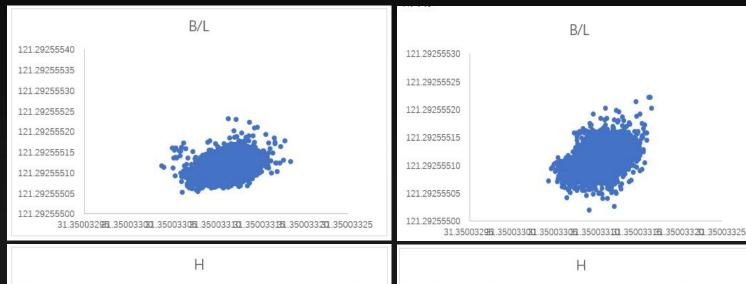
QZSS: L1C/A, L2C, L5, L1C*

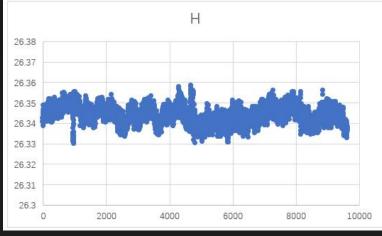
SBAS: L1C/A

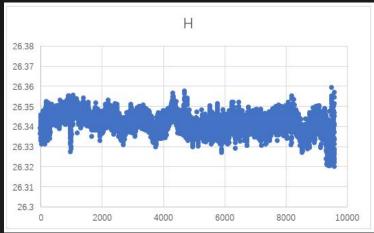
IRNSS: L5

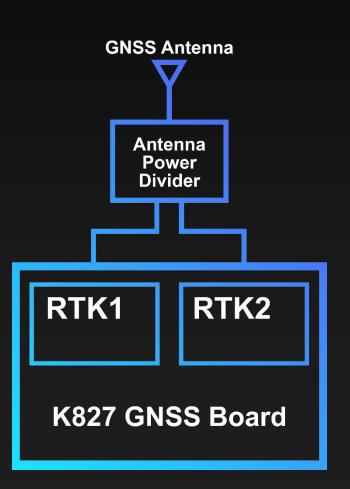


Dual-engine RTK performance









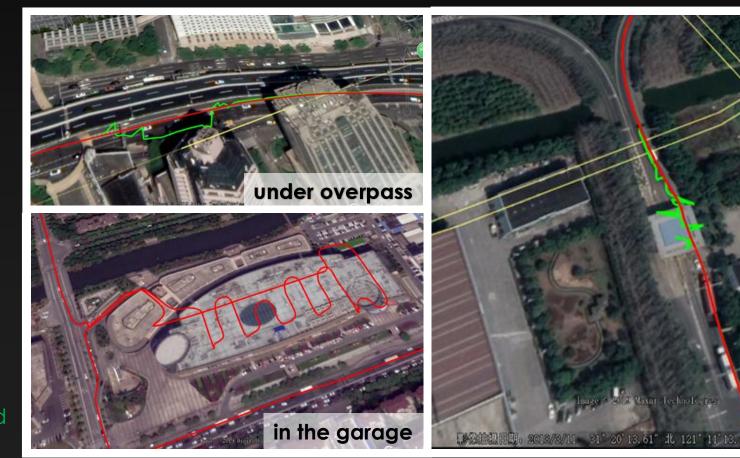


Google Fa

at toll station

Continuous positioning during lock-lose

GNSS+INS navigation



Red: IMU enabled

Green: IMU disabled











Targeted applications

Meet the demand for professional areas

Autonomous driving

UAV

Land surveyingPrecision agriculture

Machine control Robotics





K801 GNSS Module

loT at your fingertips

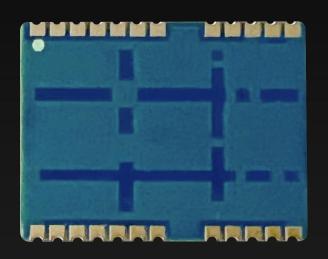


Highly integrated

Optimized for size-constrained devices



Size: $12\text{mm} \times 16 \text{ mm} \times 2.4 \text{ mm}$ Power consumption: 0.15W



2 x 12pin

2 LVTTL ports

1 SPI

1 Event Marker input

1 PPS



High reliable positioning accuracy

Dual-band multi-constellation

Positioning

GPS: L1 C/A, L5

BeiDou:B11, B2a

GALILEO:E1, E5a

GLONASS:G1

SBAS:WAS, EGNOS, MSAS, GAGAN, SDCM

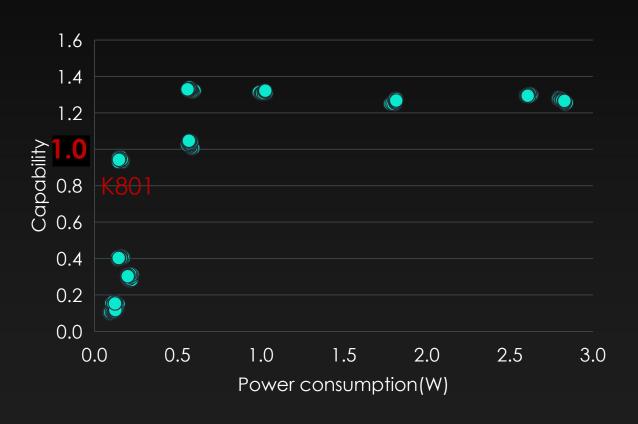
QZSS:L1 C/A, L5



Tracking satellites:45



Ultra-low power consumption



Low power consumption

High sensitivity

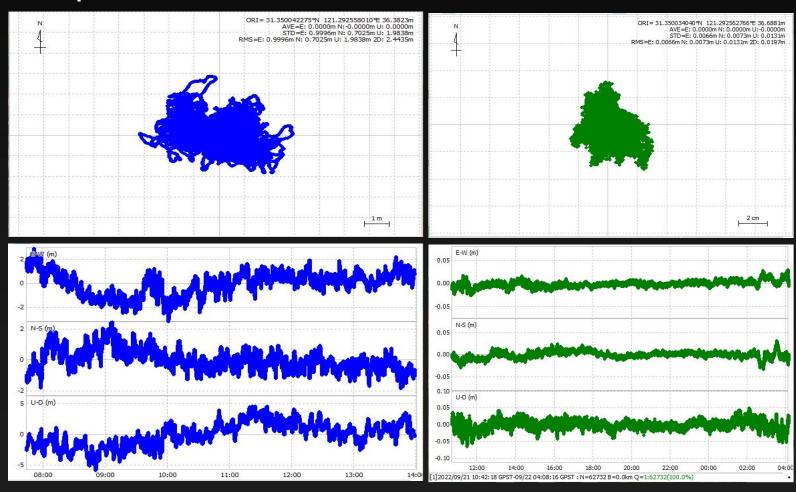
Advanced algorithm

*The preceding data are theoretical value based on experimental environments. The actual value may vary in different conditions.



Centimeter & sub-meter level accuracy

Static performance



SBAS Mode: sub-meter

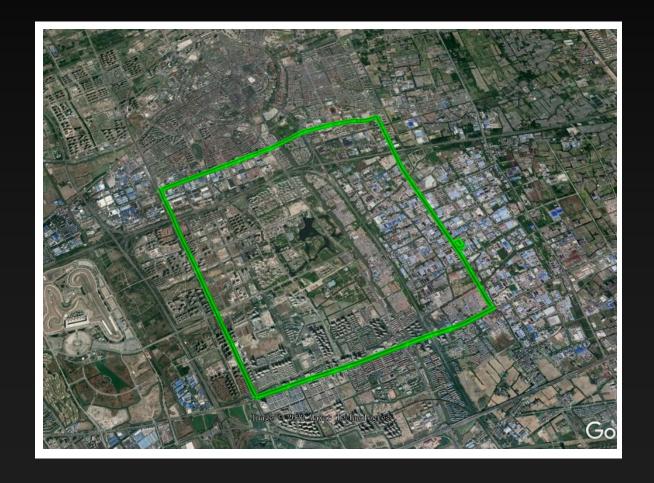
RTK mode: centimeter

Test performance

Dynamic vehicle-Mounted

- K801's dynamic navigation perform better in harsh environments such as urban canyon and overpass.
- K801 can output reliable
 positioning results where other modules cannot maintain fixed RTK solutions.





Test performance

Dynamic vehicle-Mounted



under canyon

K801: smooth and continuous

path

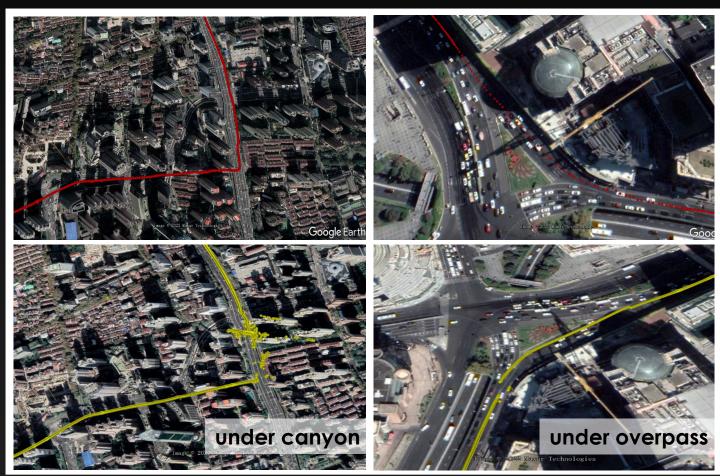
Other: offset

under overpass

K801: reliable

Other: unreliable

Yellow: Other Red: K801















Targeted applications

Consuming grade market

Wearable devices

Precision agriculture

Drones
Robotics



K8 series comparision

Model	K801	K803	K823	K827
Frequency	Dual-frequency	Triple-frequency	Multi-frequency	Multi-frequency
GPS	L1 C/A, L5	L1, L2, L5	L1, L2	L1C/A, L1C, L2P, L2C, L5
BDS	B11, B2a	B1, B2, B3	B11, B31,B1C*	B11, B21, B31, B1C, B2a, B2b
GLONASS	G1	L1, L2	L1, L2	G1, G2, G3
Galileo	E1, E5a	E1, E5a, E5b	E1, E5b	E1, E5b, E5a, E5 AltBoC*, E6c
QZSS	L1 C/A, L5	L1	L1, L2*	L1C/A, L2C, L5, L1C*
IRNSS	-	L5	-	L5
SBAS	L1	L1, L5	L1	L1C/A
L-Band	-	+	+	+
Power Consumption(W)	0.15	1W	1.6	1.8
Onboard IMU	Support	Support	Support	Support

[&]quot;-" do not support "*" upgradable "+" conditional support



THANKS FOR ATTENDING

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